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Interconnecting and harmonizing of ITS mobility clouds

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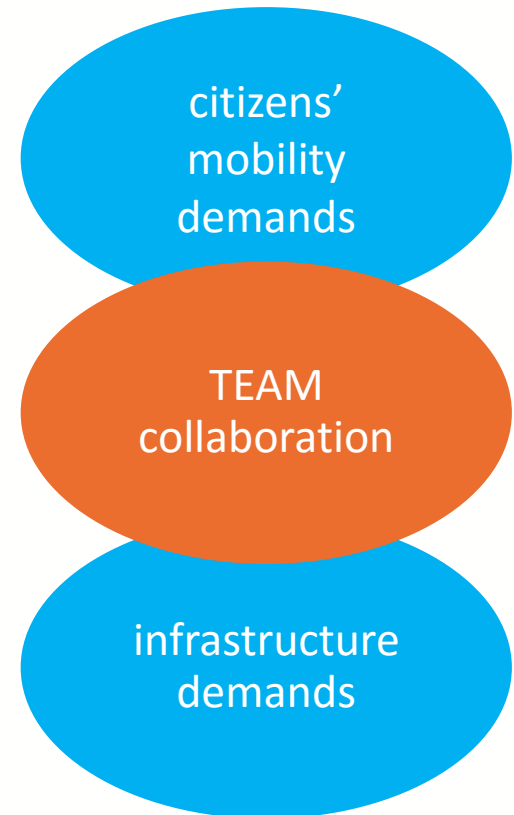
TEAM mission: Turn static into elastic mobility by balancing needs.

Collaboration is the key concept.

It extends the cooperative concept of vehicle-2-x systems to include interaction and participation.

Make travellers and drivers, vehicles and infrastructure act as a **TEAM**

- Adapting to each other
- Adapting to the situation



Collaborative applications

3 from 11 applications developed and tested in TEAM

Collaborative eco-friendly navigation

- merges all information (from road users, traffic data, infrastructure) to create collaborative eco-friendly routing and navigation

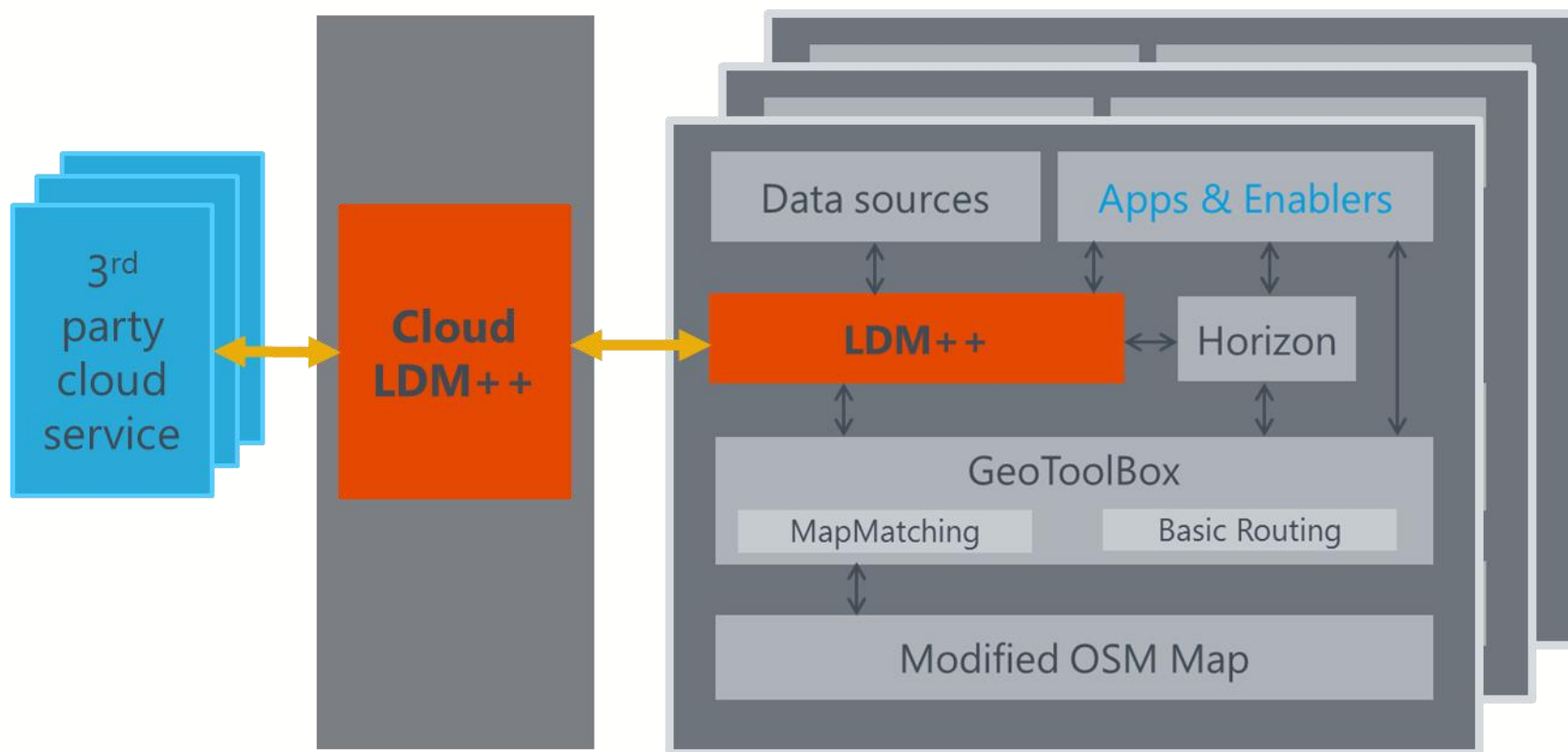
Collaborative co-modal route planning

- provides end-users with alternative routes and transportation modes based on their preferences

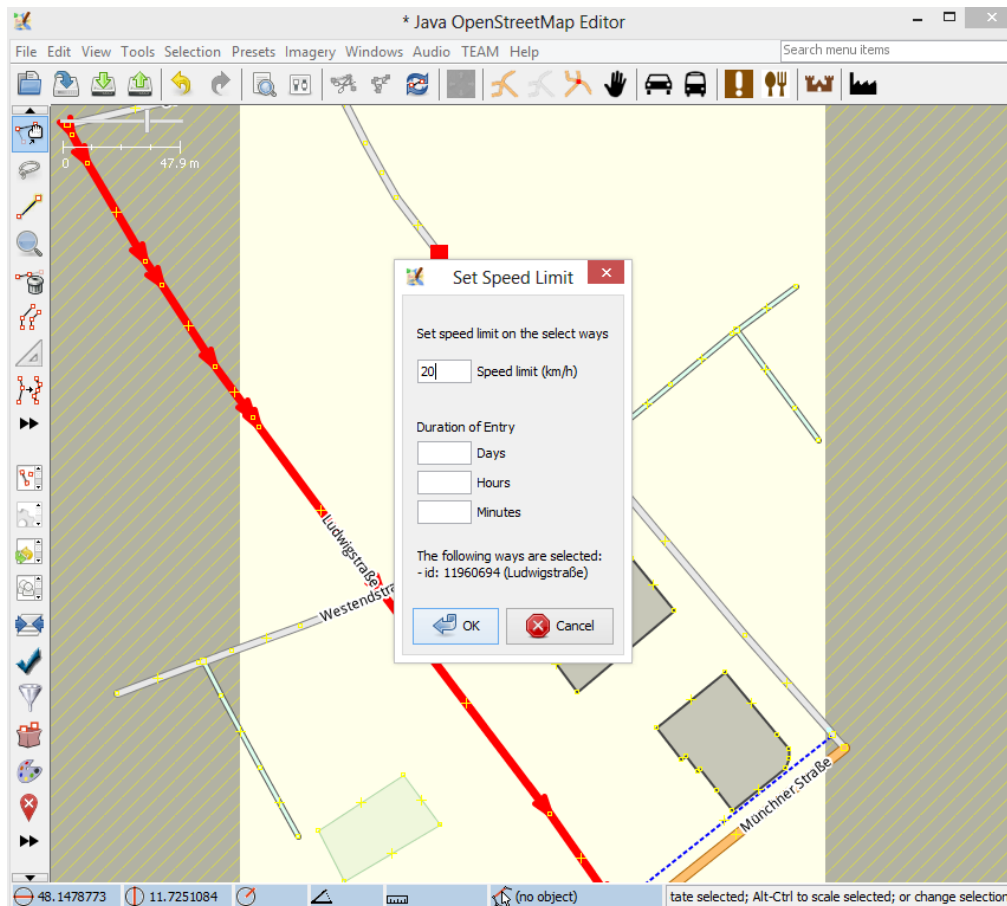
Collaborative adaptive cruise control

- adapts vehicle speed to optimize traffic, reducing velocity deviations and fuel consumption

Open Cloud Solution: LDM++



Collaborative navigation I (CONAV and COPLAN)



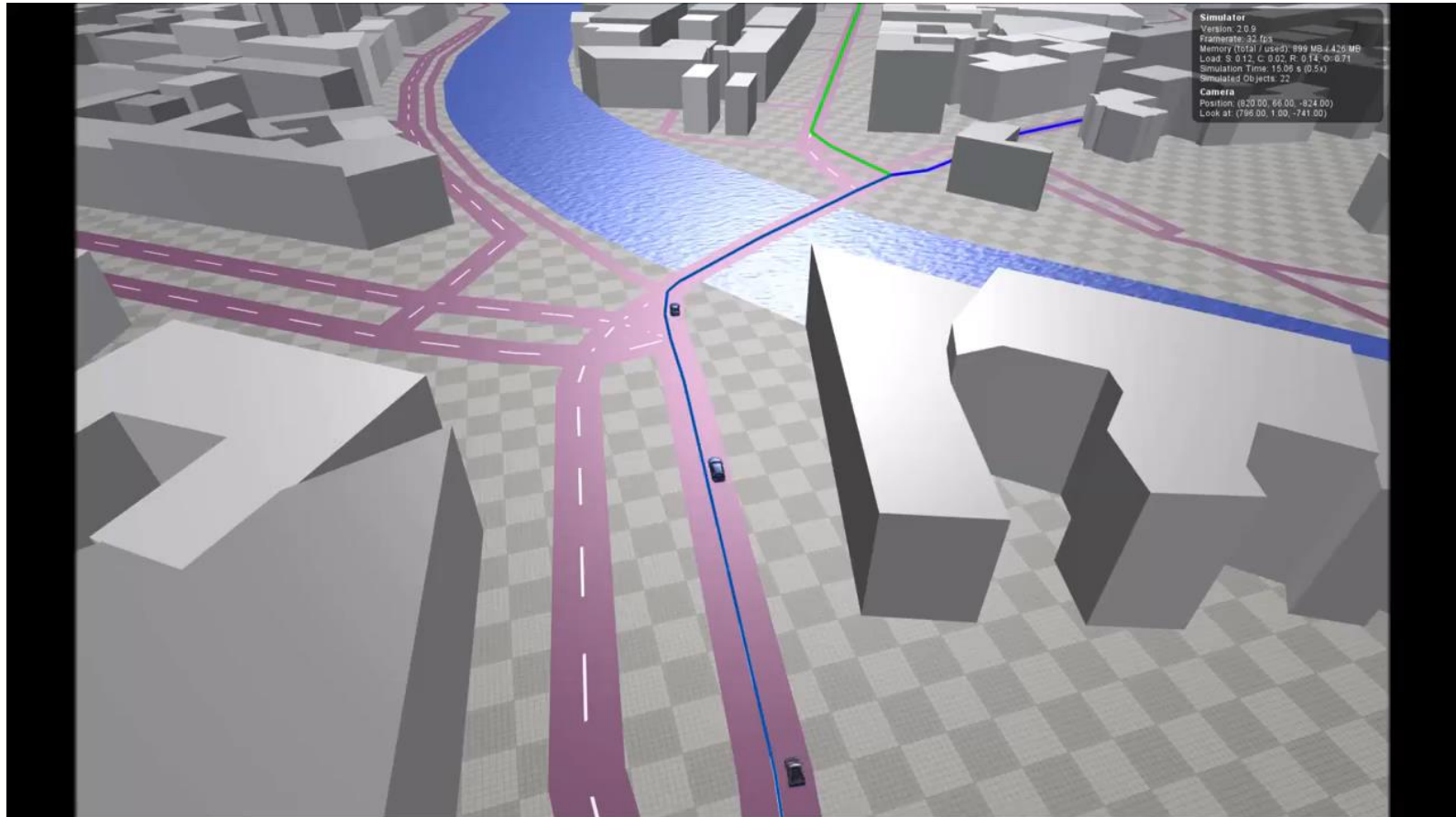
Traffic managers are able to edit network features

- Speed limits
- Road blockings

Information is pushed to cloud LDM++.

The routing engine is a subscriber of the relevant channel. It considers the updated information.

Collaborative navigation II (CONAV and COPLAN)

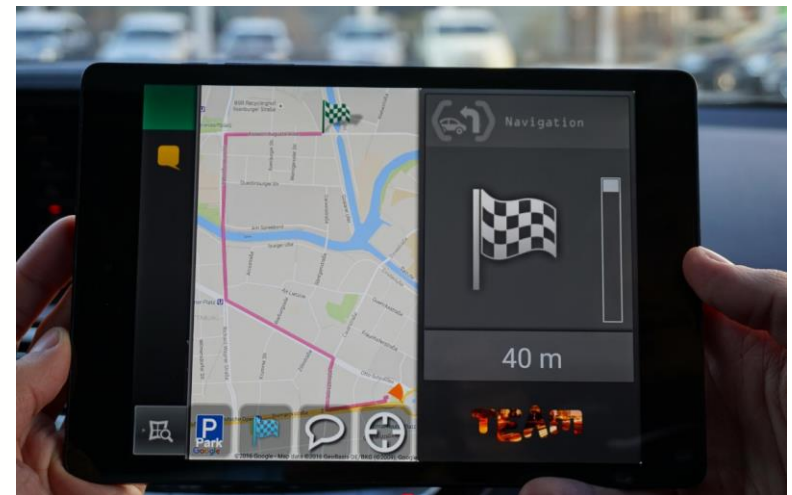


Applications deployed to TEAM pilots sites

Berlin, Turin, Gothenburg, Tampere, Athens, Trikala, Trento



Standalone smartphone version in Athens



Vehicle-integrated version in Berlin

TEAM consortium



Automotive



ICT



Infra-structure



Research



Other



Save the date!



A graphic for a 'Save the Date' announcement. It features a large blue speech bubble with the text 'SAVE THE DATE' and 'Final Event' in white, and '18-19 October 2016' in orange. Below the bubble is a row of colorful icons representing various modes of transport: a person on a bicycle, a person walking, a car, a person on a bicycle, a person on a scooter, a person on a motorcycle, a person on a bicycle, a person on a scooter, a person on a motorcycle, a person on a bicycle, a person on a scooter, a person on a motorcycle. Below the icons is a grey rectangular box with the text: 'TEAM evolves traditional mobility patterns to become **elastic** by joining all traffic participants and infrastructure operators together into one collaborative network.' Below this box is the text: 'Join us for demonstrations, conference and exhibition at EUREF Campus, Berlin, Germany'. At the bottom left is the website 'www.collaborative-team.eu'. At the bottom right is the text 'This project is co-funded by the European Union' next to the European Union flag.

SAVE THE DATE

Final Event

18-19 October 2016

TEAM Tomorrow's Elastic Adaptive Mobility

TEAM evolves traditional mobility patterns to become **elastic** by joining all traffic participants and infrastructure operators together into one collaborative network.

Join us for demonstrations, conference and exhibition at EUREF Campus, Berlin, Germany

www.collaborative-team.eu

This project is co-funded by the European Union

Thank you.



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Cloud LDM++ web access



The screenshot shows the LDM++ Cloud web interface. At the top, there's a navigation bar with 'LDM++ CLOUD' and 'CLIENTS'. Below this, the 'Overview' section displays a table with key metrics:

Key	Value
Open long-polling connections	4
Channel count	21
Total object count	367

Below the overview, the 'Channels' section displays a table with the following data:

ID	Name	Creation	Cloud	Map-matched	z/m	Objects	Subscriptions	Description
-1	meta-channel-def	static	syncd	no	0.0	3	4	Contains meta-data of dynamic channels
1	SMARTINTERSECTION	static	syncd	yes	2.5	167	4	
2	PARKING	static	syncd	yes	2.5	65	4	
3	TRAFFICJAM	static	syncd	yes	2.5	0	4	
4	ROADWORKS	static	syncd	yes	2.5	89	4	
5	CARSHARING	static	syncd	yes	2.5	0	4	
6	LINKSPEED	static	syncd	yes	2.5	0	4	
7	CAM	static	local	no	2.5	0	4	
8	DENM	static	local	no	2.5	0	4	
9	YAHOOWEATHER	static	syncd	yes	2.5	0	4	
10	CURVEWARNING	static	syncd	yes	2.5	0	4	
11	PTDATA	static	syncd	yes	2.5	0	4	Public transport data
12	LRDATA	static	syncd	yes	2.5	0	4	Lane restriction data
13	PARKINGZONES	static	syncd	yes	2.5	31	4	Static parking-zone data
14	PARKEVENTS	static	syncd	yes	2.5	0	4	Park events, i.e. on taking or leaving parking spots
15	FORECAST	static	syncd	yes	2.5	0	4	
16	COPLAN	dynamic	syncd	no	-1.0	0	4	COPLAN channel
101	Intersection-whitelist	dynamic	syncd	yes	1.5	12	4	
130	TRAFFICEVENTS	static	syncd	yes	2.5	0	4	
131	TRAFFIONFORMATION	static	local	yes	2.5	0	4	
2000	bmw-weather	dynamic	syncd	yes	2.5	0	4	Weather events from BMW cloud

Data in the TEAM cloud

- Road-side parking information
- Traffic flow information at all TEAM pilot sites (Athens, Berlin, Tampere, Turin, Gothenburg)
- Weather information from public Internet service and BMW
- Traffic light information
- Public transport schedules
- Roadworks
- ...